

Tutorial on Variational Autoencoder and its Gradient Estimators

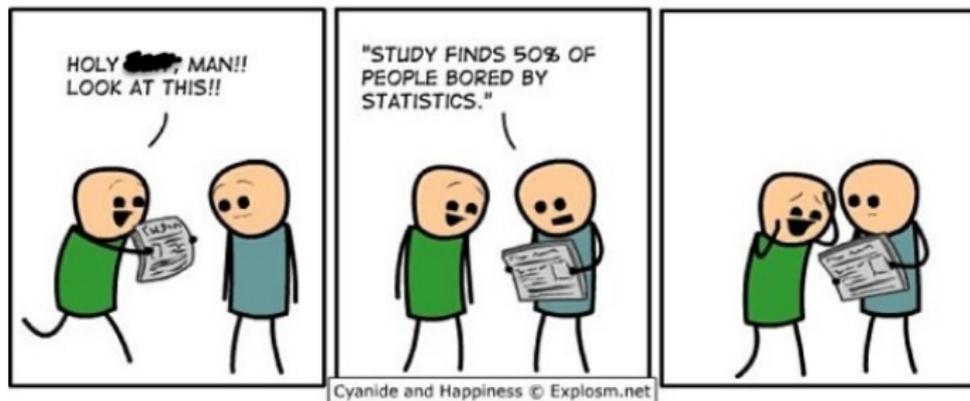


Raymond A. Yeh

University of Illinois at Urbana-Champaign

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Motivation



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- Suppose we are interested in modeling the distribution of

$$p_{\theta}(\mathbf{x}, \mathbf{z}) = p_{\theta}(\mathbf{x}|\mathbf{z})p(\mathbf{z}) \quad (1)$$

where only \mathbf{x} is observed and \mathbf{z} is an unobserved variable.

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- To apply maximum-likelihood,

$$p_{\theta}(\mathbf{x}) = \int p_{\theta}(\mathbf{x}, \mathbf{z}) d\mathbf{z} \quad (2)$$

- Is this integral tractable?
- Can we approximate it? $p_{\theta}(\mathbf{x}) \approx \sum_{\mathbf{z}^{(i)}} p_{\theta}(\mathbf{x}|\mathbf{z}^{(i)})$,

where $\mathbf{z}^{(i)} \sim p(\mathbf{z})$.

Variational inference

- Sampling problem \rightarrow optimization problem.
- Evidence Lower Bound (ELBO)

$$\begin{aligned}\log p_{\theta}(\mathbf{x}) &= \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log p_{\theta}(\mathbf{x}) d\mathbf{z} \\ &= \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log \left(p_{\theta}(\mathbf{x}) \frac{p_{\theta}(\mathbf{z}|\mathbf{x}) q_{\phi}(\mathbf{z}|\mathbf{x})}{p_{\theta}(\mathbf{z}|\mathbf{x}) q_{\phi}(\mathbf{z}|\mathbf{x})} \right) d\mathbf{z} \\ &= \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log \left(\frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q_{\phi}(\mathbf{z}|\mathbf{x})} \right) d\mathbf{z} - \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log \left(\frac{p_{\theta}(\mathbf{z}|\mathbf{x})}{q_{\phi}(\mathbf{z}|\mathbf{x})} \right) d\mathbf{z} \\ &= \mathbb{E}_{q_{\phi}} \left[\log \frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q_{\phi}(\mathbf{z}|\mathbf{x})} \right] + KL(q_{\phi}||p_{\theta}) \\ &\geq \mathbb{E}_{q_{\phi}} \left[\log \frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q_{\phi}(\mathbf{z}|\mathbf{x})} \right] = \mathcal{L}(\phi, \theta)\end{aligned}$$

Evidence lower bound (ELBO)

- When is ELBO tight? $\mathbb{E}_{q_\phi} \left[\log \frac{p_\theta(\mathbf{x}, \mathbf{z})}{q_\phi(\mathbf{z}|\mathbf{x})} \right] + KL(q_\phi || p_\theta) \geq \mathcal{L}(\phi, \theta)$
 - To get the tightest bound, find q_ϕ such that maximizes ELBO.

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- Further decompose:
$$\mathbb{E}_{q_\phi} \left[\log \frac{p_\theta(\mathbf{x}, \mathbf{z})}{q_\phi(\mathbf{z}|\mathbf{x})} \right] = \mathbb{E}_{q_\phi} [\log(p_\theta(\mathbf{x}|\mathbf{z}))] - KL(q_\phi(\mathbf{z}|\mathbf{x}) || p(\mathbf{z}))$$
 - Estimate the first term using Monte Carlo samples.
 - KL can be computed analytically, if q and p are “simple”.

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- **Side Note:** EM algorithm is choosing $q_\phi(\mathbf{z}|\mathbf{x})$ as $p_{\theta^{t-1}}(\mathbf{z}|\mathbf{x})$, *i.e.* assumes the computation of the posterior is tractable.
- Need to choose a “flexible” $q_\phi(\mathbf{z}|\mathbf{x})$ that is also easy to sample from. How? Deep nets!

Variational AutoEncoder (VAE)

- Variational AutoEncoder models both $p_{\theta}(\mathbf{x}|\mathbf{z})$ and $q_{\phi}(\mathbf{z}|\mathbf{x})$ with deep networks:
 - Encoder: $q_{\phi}(\mathbf{z}|\mathbf{x}) \sim \mathcal{N}(\mu_{\phi}(\mathbf{x}), \sigma_{\phi}(\mathbf{x}) \cdot \mathbf{I})$
 - Decoder: $p_{\theta}(\mathbf{x}|\mathbf{z}) \sim \mathcal{N}(\mu_{\theta}(\mathbf{z}), c \cdot \mathbf{I})$

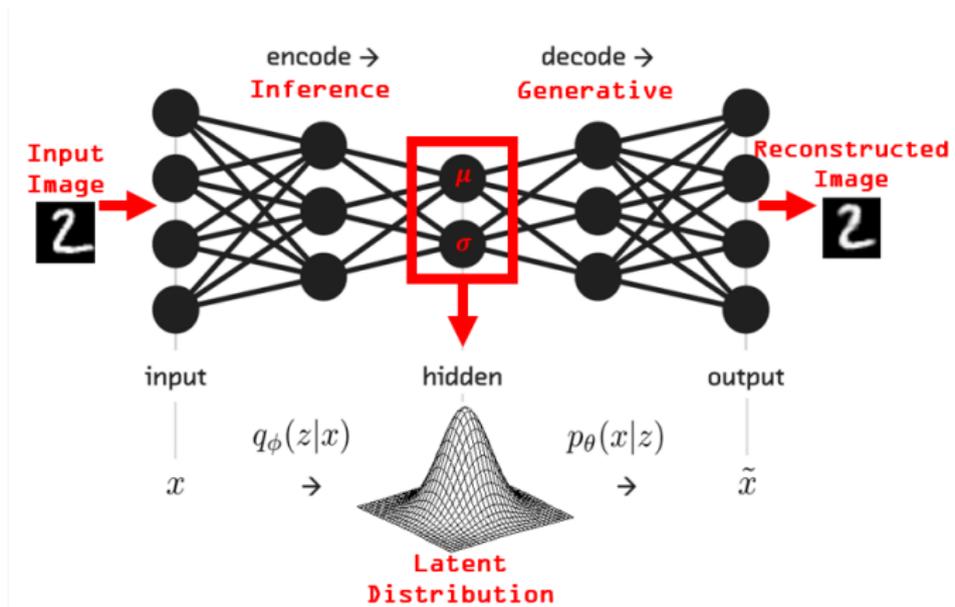
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- How to learn ϕ ?:
 - Reparameterization Trick:
 $\mathbf{z} \sim \mathcal{N}(\mu, \sigma)$ is equivalent to $\mu + \sigma \cdot \epsilon$ where $\epsilon \sim \mathcal{N}(0, 1)$.
 - Sample \mathbf{z} from q is a deterministic function of ϵ .
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- How to learn θ ? Standard backpropagation.

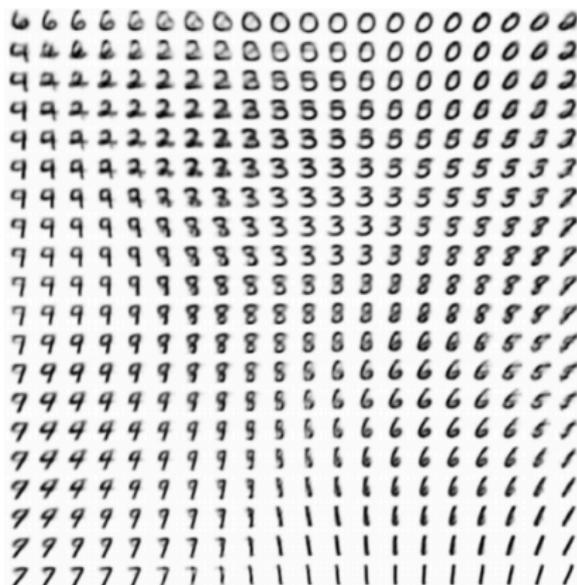
Overall pipeline



Applications



(a) Learned Frey Face manifold



(b) Learned MNIST manifold

Since the original VAE paper...

- Extension to the family of $q_\phi(z)$
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Lower variance gradient estimator

- ELBO

$$\mathcal{L}(\phi) = \mathbb{E}_{\mathbf{z} \sim q_{\phi}(\mathbf{z}|\mathbf{x})}[\log p(\mathbf{x}|\mathbf{z})] - KL(q_{\phi}(\mathbf{z}|\mathbf{x})||p(\mathbf{z})) \quad (3)$$

$$= \mathbb{E}_{\mathbf{z} \sim q_{\phi}(\mathbf{z}|\mathbf{x})}[\log(p(\mathbf{x}|\mathbf{z})) + \log(p(\mathbf{z})) - \log(q_{\phi}(\mathbf{z}|\mathbf{x}))] \quad (4)$$

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- Gradient estimator, let $\mathbf{z} = t(\epsilon, \phi)$

$$\begin{aligned} \hat{\nabla}_{TD} &= \nabla_\phi [\log p(\mathbf{x}, \mathbf{z}) - \log q_\phi(\mathbf{z}|\mathbf{x})] \\ &= \underbrace{\nabla_{\mathbf{z}} [\log p(\mathbf{x}, \mathbf{z}) - \log q_\phi(\mathbf{z}|\mathbf{x})]}_{\text{path derivative}} \nabla_\phi t(\epsilon, \phi) - \underbrace{\nabla_\phi \log q_\phi(\mathbf{z}|\mathbf{x})}_{\text{score function}} \end{aligned}$$

For any finite samples of \mathbf{z} the score function is not necessarily zero, even when $q_\phi(\mathbf{z}|\mathbf{x}) = p_\theta(\mathbf{z}|\mathbf{x})$.

Lower variance gradient estimator

- Remove the score function?

$$\hat{\nabla}_{PD} = \underbrace{\nabla_{\mathbf{z}}[\log p(\mathbf{x}, \mathbf{z}) - \log q_{\phi}(\mathbf{z}|\mathbf{x})]}_{\text{path derivative}} \nabla_{\phi} t(\epsilon, \phi) - \underbrace{\nabla_{\phi} \log q_{\phi}(\mathbf{z}|\mathbf{x})}_{\text{score function}}$$

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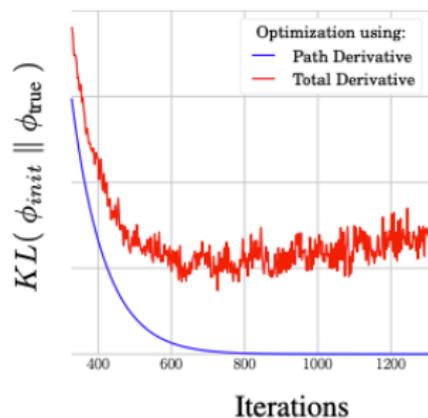
- Remove the score function?

$$\hat{\nabla}_{PD} = \underbrace{\nabla_{\mathbf{z}}[\log p(\mathbf{x}, \mathbf{z}) - \log q_{\phi}(\mathbf{z}|\mathbf{x})]}_{\text{path derivative}} \nabla_{\phi} t(\epsilon, \phi) - \underbrace{\nabla_{\phi} \log q_{\phi}(\mathbf{z}|\mathbf{x})}_{\text{score function}}$$

- The score function has expected value of zero, thus $\hat{\nabla}_{PD}$ is an unbiased estimator. Proof:

$$\begin{aligned}\mathbb{E}_{q(\mathbf{z}|\mathbf{x})}[\nabla_{\phi} \log q_{\phi}(\mathbf{z}|\mathbf{x})] &= \int \left(\nabla_{\phi} \log q_{\phi}(\mathbf{z}|\mathbf{x}) \right) q(\mathbf{z}|\mathbf{x}) d\mathbf{z} \\ &= \int \left(\nabla_{\phi} q_{\phi}(\mathbf{z}|\mathbf{x}) \right) d\mathbf{z} \\ &= \nabla_{\phi} \int q_{\phi}(\mathbf{z}|\mathbf{x}) d\mathbf{z} = 0\end{aligned}$$

Lower variance gradient estimator



$\log p(x, z) - \log q_\phi(z|x)$ Surface Along Trajectory through True ϕ

